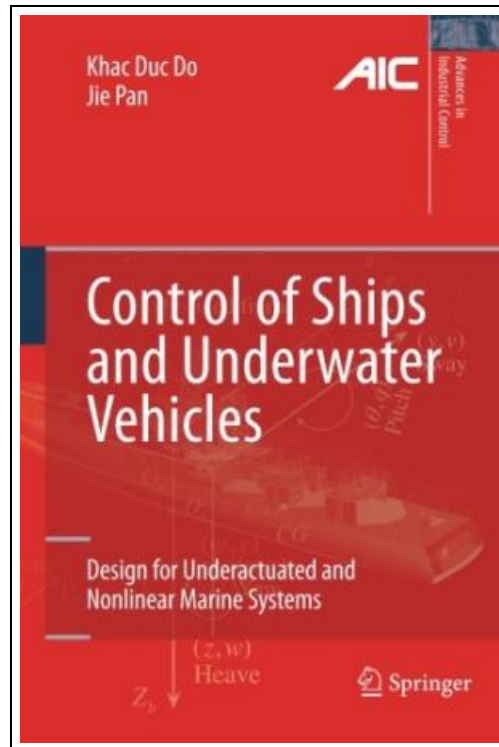


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CONTROL OF SHIPS AND UNDERWATER VEHICLES: DESIGN FOR UNDERACTUATED AND NONLINEAR MARINE SYSTEMS



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