



Enovia V5-6r2015: Dmu Kinematics (Paperback)

By Ascent - Center for Technical Knowledge

Ascent, Center for Technical Knowledge, United States, 2017. Paperback. Condition: New. Language: English . Brand New Book ***** Print on Demand *****. The ENOVIA V5-6R2015: DMU Kinematics student guide focuses on how to create and simulate V5 mechanisms using CATIA products. The course begins with an overview of the mechanism design process and then each step in the process is discussed in depth using lectures and hands-on practices. This course also introduces the concept of converting assembly constraints into kinematic joints. Additionally, this student guide provides an introduction to converting V4 mechanisms to V5 as well as the 3D model method of creating kinematic assemblies. Topics Covered Kinematic analysis process Constraintbased joints Curve/surface-based joints Ratio-based joints Compiling and replaying a simulation Swept volumes Traces Sensors Clash detection Assembly constraint conversion CATIA V4 mechanisms Simulation with laws Prerequisites ENOVIA V5-6R2015: DMU Navigator and Space Analysis CATIA V5-6R2015: Introduction to Modeling CATIA V5-6R2015: Introduction for Non-Designers.



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