



## Robot Motion Control Using DIP

By Lokhande, Narendra L. / Bhole, Pravin R.

Condition: New. Publisher/Verlag: LAP Lambert Academic Publishing | The Robot design which having the motion control with the help of finger acknowledgment/ball motion of user. The technique used is a Digital Image Processing (DIP) through which the different position of a ball sends the different signals towards the control section at Micro controller Unit (MCU). The Image Acquisition Tools here used is Matlab and the image recognition device is a Webcam. we are using the physical motion of fingers to control the physical motion of the robot by means of digitization of image. The physical motion control in system using physical acknowledgment with use of digital process and interaction. | Format: Paperback | Language/Sprache: english | 72 pp.



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