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A HAPTIC CONTROL FRAMEWORK FOR END-EFFECTOR BASED GAIT SIMULATION INTERFACES AND ITS APPLICATION IN PATIENT-ADAPTIVE REHABILITATION TRAINING



Fraunhofer Verlag Dez 2012, 2012. Taschenbuch. Condition: Neu. Neeware - The use of robots to assist therapy of neurological motor disfunctions, such as limited mobility, is an emerging research field. This book provides the first systematic application of a haptic control framework and assist as needed training paradigms to so called end-effector based gait simulation interfaces with a natural walking workspace, which fully carry the operator's bodyweight. The developed haptic control framework provides a unified controller architecture and a design...

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- Authored by Sami Hussein
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